

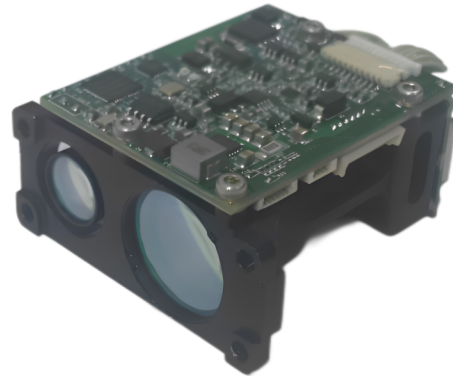
# 1535nm Laser Rangefinder-4K10

SKU:LRF1535-4K10



## OVERVIEW

The LRF1535-4K10 eye-safe ranging module is developed based on ERDI TECH's independently researched and developed erbium glass laser. The main features of this laser rangefinder are: long detection range, small size, light weight, fast response time, high detection accuracy, and the ability to detect multiple targets. The output target distance data can be integrated into the battlefield communication network. It can measure vehicle targets at a distance of over 4000 meters and human targets at a distance of over 2000 meters.

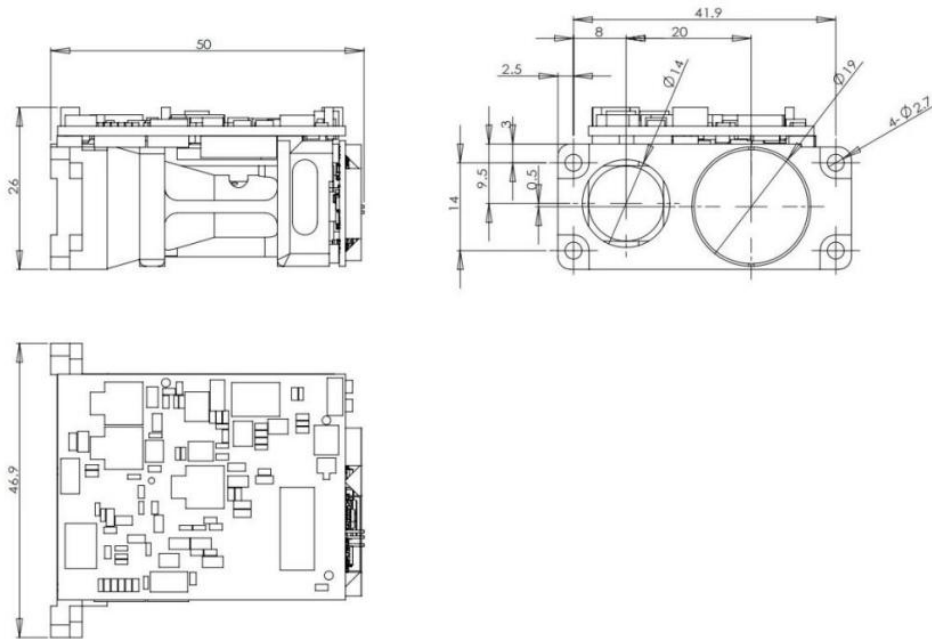


## TECHNICAL SPECIFICATIONS

Item	Technical parameter	
Laser wavelength	1.54μm	
Ranging capability	20m~4km	2.3m×2.3m vehicle target, 0.3 diffuse reflectance, visibility ≥5km
	20m~10km	Energy intensity ≥ 10km, 0.3 large reflectivity target
Voltage of operation	4.5V~16V	
False alarm rate	≤1%	
Quasi measurement rate	≥98%	
Minimum geodesic range	20m	
Standby current	≤0.01A (8V power supply)	
Divergence angle	≤0.5mrad	
Accuracy	0.25m~±2m	
Frequency of operation	1 Hz, 5 Hz, emergency 10Hz	
Ranging logic	First and last target selection	
Output interface	RS422	
Storage property	Storage life 12 years	
Dimension	48×36×26	
Weight	44.5g	
Operating temperature	-40°C~+ 55°C	
Temperature of storage	-50°C~ +85°C	



## MECHICAL INTERFACE



## COMMUNICATION INTERFACE

External circuit interface of laser rangefinder adopts external socket, which has the function of external power interface and data communication. External socket 1.25mm spacing 8-core socket, specific pin definition is shown in the table below:

Pin	Symbol	Function	Description
1	T+	Communication signal	Connect PC RX+
2	T-	Communication signal	Connect PC RX-
3	R-	Communication signal	Connect PC TX-
4	R+	Communication signal	Connect PC TX+
5	GND	Place of communication	
6	GND	Power Ground	
7	+8V/2A	Total power supply	
8	+8V/2A	Total power supply	

## COMMUNICATION COMMAND CHART

RS422 communication, baud rate 115200

The rangefinder receives a work command and triggers the laser to work according to the command, and then replies to the host computer with the range information after completing a range according to the period of the work command.

The following are all in hexadecimal

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## Uplink to rangefinder command

4 bytes AA for the head, 0C for the tail, 01, 02, 03 for the command word

AA 01 (01-0A)0C Automatic ranging from 1-10Hz

AA 01 0B 0C Enhanced ranging according to 1Hz

AA 02 00 0C Stop auto-ranging

AA 03 00 0C Single ranging

## Rangefinder to host computer reply message

55 is the head 0D is the tail 04, 05, 15, 35 is the command word

No laser 55 04 00 00 00 00 00 0D

With laser without echo 55 05 00 00 00 00 0D      Goal 1 is 0, Goal 2 is 0

There is a laser with a target 55 15 DIS1H DIS1L 00 00 0D      Target 1 has value, target 2 is 0

There are lasers with two targets 55 35 DIS1H DIS1L DIS2H DIS2L 0D      Goal 1 has value, Goal 2 has value

Example:Distance value 100 means 25m, 101 means 25.25m, 102 means 25.50m, 103 means 25.75m.